

Applied Linear Algebra

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Chapter 8

Symmetric Matrices and Quadratic Forms

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8.1 SYMMETRIC MATRICES

In chapter 7, we are concerned with when is a given square matrix A diagonalizable? That is, when is there an eigenbasis for A ?

In geometry, we prefer to work with orthonormal bases, which raises the question:

For which matrices is there an *orthonormal eigenbasis*?

Example 1 If A is orthogonally diagonalizable, what is the relationship between A^T and A ?

Solution We have

$$S^{-1}AS = D$$

or

$$A = SDS^{-1} = SDS^T$$

for an orthogonal matrix S and a diagonal D .
Then

$$A^T = (SDS^T)^T = SD^T S^T = SDS^T = A.$$

We find that A is symmetric.

Fact 8.1.1 Spectral theorem

A matrix A is orthogonally diagonalizable if and only if A is symmetric (i.e., $A^T = A$).

The set of eigenvalues of a matrix is called the spectrum of A , and the following description of the eigenvalues is called a spectral theorem.

THEOREM

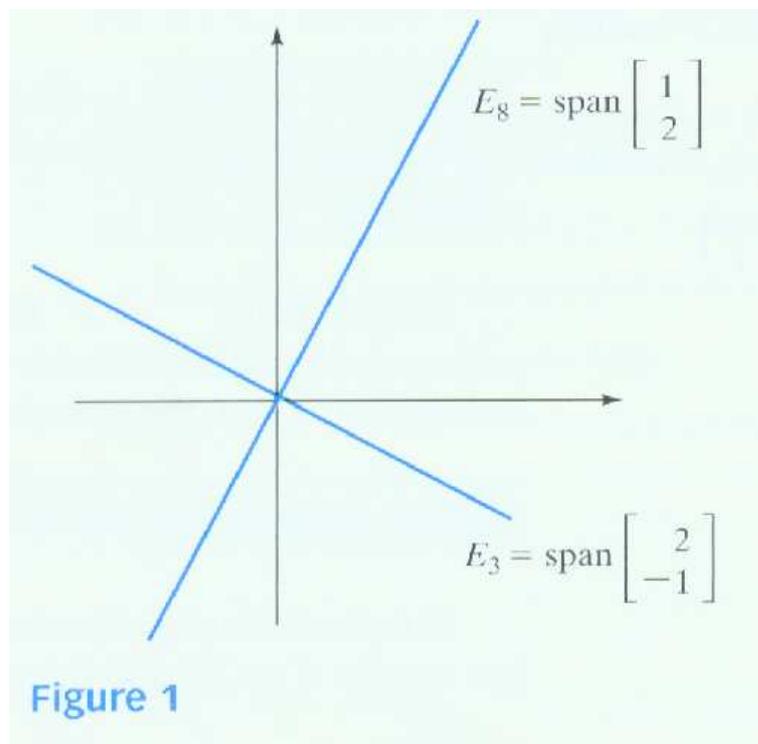
The Spectral Theorem For A Symmetric Matrix

- A has n real eigenvalues, counting multiplicities. (Fact 8.1.3)
- The dimension of the eigenspace for each eigenvalue λ equals the algebraic multiplicity of λ .
- The eigenspaces are mutually orthogonal, in the sense that eigenvectors corresponding to different eigenvalues are orthogonal. (Fact 8.1.2)
- A is orthogonally diagonalizable. (Fact 8.1.1)

Example 2 For the symmetric matrix $A = \begin{bmatrix} 4 & 2 \\ 2 & 7 \end{bmatrix}$, find an orthogonal S such that $S^{-1}AS$ is diagonal.

Solution See Figure 1.

$$E_3 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}, E_8 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$



Note that the eigenspaces E_3 and E_8 are perpendicular. (This is no coincidence.) Therefore, we can find an orthonormal eigenbasis simply by dividing the given eigenvectors by their lengths:

$$\vec{v}_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ -1 \end{bmatrix}, \vec{v}_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Define

$$S = \begin{bmatrix} | & | \\ \vec{v}_1 & \vec{v}_2 \\ | & | \end{bmatrix} = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix}$$

$$\text{then } S^{-1}AS = \begin{bmatrix} 3 & 0 \\ 0 & 8 \end{bmatrix}$$

Fact 8.1.2 Consider a symmetric matrix A . If \vec{v}_1 and \vec{v}_2 are eigenvectors of A with distinct eigenvalues λ_1 and λ_2 , then $\vec{v}_1 \cdot \vec{v}_2 = 0$; that is, \vec{v}_2 is orthogonal to \vec{v}_1 .

Proof We compute the product $\vec{v}_1^T A \vec{v}_2$ in two ways:

- $\vec{v}_1^T A \vec{v}_2 = \vec{v}_1^T (\lambda_2 \vec{v}_2) = \lambda_2 (\vec{v}_1 \cdot \vec{v}_2)$
- $\vec{v}_1^T A \vec{v}_2 = \vec{v}_1^T A^T \vec{v}_2 = (A \vec{v}_1)^T \vec{v}_2 = (\lambda_1 \vec{v}_1)^T \vec{v}_2 = \lambda_1 (\vec{v}_1 \cdot \vec{v}_2)$

Comparing the results, we find

$$\lambda_1 (\vec{v}_1 \cdot \vec{v}_2) = \lambda_2 (\vec{v}_1 \cdot \vec{v}_2)$$

or

$$(\lambda_1 - \lambda_2) (\vec{v}_1 \cdot \vec{v}_2) = 0$$

Since $\lambda_1 \neq \lambda_2$, $\vec{v}_1 \cdot \vec{v}_2$ must be zero.

Fact 8.1.3 A symmetric $n \times n$ matrix A has n real eigenvalues if they are counted with their algebraic multiplicities.

Proof of 8.1.3 For those who have studied Section 7.5. Consider two complex conjugate eigenvalues $p \pm iq$ of A with corresponding eigenvectors $\vec{v} \pm i\vec{w}$. Compute the product

$$(\vec{v} + i\vec{w})^T A(\vec{v} - i\vec{w})$$

in two different ways:

$$\begin{aligned} (\vec{v} + i\vec{w})^T A(\vec{v} - i\vec{w}) &= (\vec{v} + i\vec{w})^T (p - iq)(\vec{v} - i\vec{w}) \\ &= (p - iq)(\|\vec{v}\|^2 + \|\vec{w}\|^2) \end{aligned}$$

$$\begin{aligned} (\vec{v} + i\vec{w})^T A(\vec{v} - i\vec{w}) &= (A(\vec{v} + i\vec{w}))^T (\vec{v} - i\vec{w}) \\ &= (p + iq)(\vec{v} + i\vec{w})^T (\vec{v} - i\vec{w}) = (p + iq)(\|\vec{v}\|^2 + \|\vec{w}\|^2) \end{aligned}$$

Comparing the results, we find that $p + iq = p - iq$, so $q = 0$, as claimed.

Proof of 8.1.1 Even more technical.

Example 3 For the symmetric matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

find an orthogonal S such that $S^{-1}AS$ is diagonal.

Solution

The eigenvalues are 0 and 3, with

$$E_0 = \text{span} \left(\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right) \text{ and } E_3 = \text{span} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Note that the two eigenspaces are indeed perpendicular to one another (See Figure 2, 3).

We can construct an orthonormal eigenbasis for A by picking an orthonormal basis of each eigenspace.

Perform Gram-Schmidt process to the vectors

$$\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

we find

$$\vec{v}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}$$

For E_3 , we get

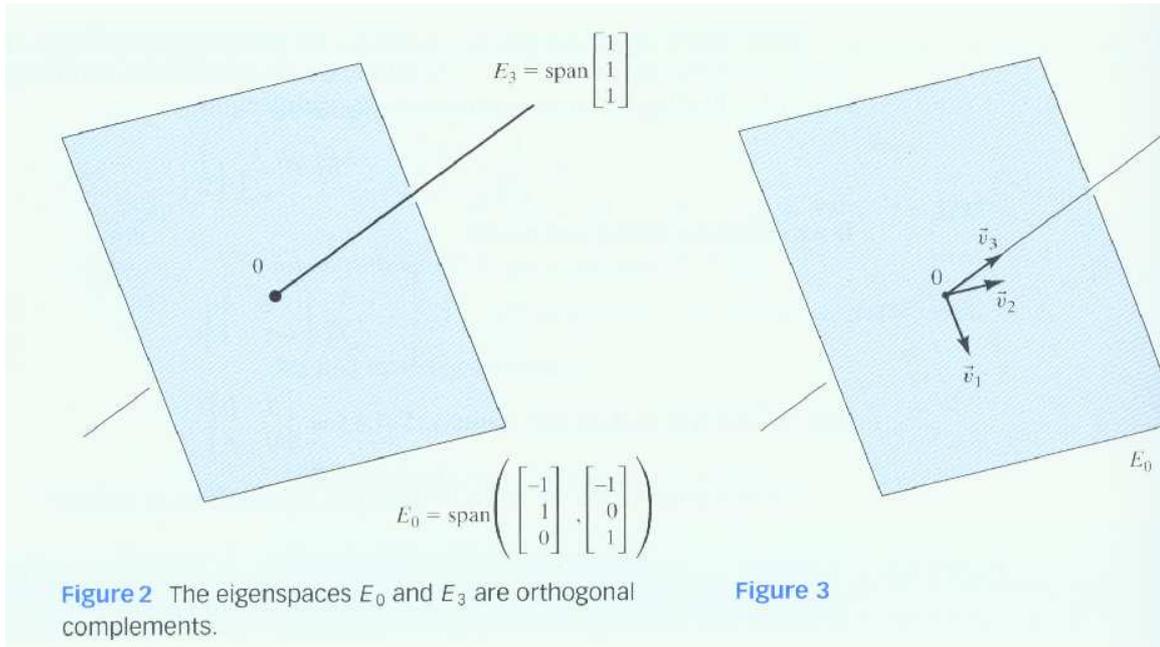
$$\vec{v}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Therefore, the orthogonal matrix

$$S = \begin{bmatrix} | & | & | \\ \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \\ | & | & | \end{bmatrix} = \begin{bmatrix} -1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & 2/\sqrt{6} & 1/\sqrt{3} \end{bmatrix}$$

diagonalizes the matrix A :

$$S^{-1}AS = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$



Algorithm 8.1.4 Orthogonal diagonalization of a symmetric matrix A

1. Find the eigenvalues of A , and find a basis of each eigenspace.
2. Using the Gram-Schmidt process, find an orthonormal basis of each eigenspace.
3. Form an orthonormal eigenbasis $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ for A by combining the vectors you find in the last step, and let

$$P = \begin{bmatrix} | & | & \dots & | \\ \vec{u}_1 & \vec{u}_2 & \dots & \vec{u}_n \\ | & | & & | \end{bmatrix}$$

P is orthogonal, and $P^{-1}AP$ will be diagonal.

Spectral Decomposition

Suppose that $A = PDP^{-1}$, where the columns of P are orthonormal eigenvectors $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ of A and the corresponding eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ are in the diagonal matrix D . Then, since $P^{-1} = P^T$,

$$\begin{aligned} A = PDP^T &= \begin{bmatrix} \vec{u}_1 & \cdots & \vec{u}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & 0 \\ & \cdots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \\ \vdots \\ \vec{u}_n^T \end{bmatrix} \\ &= \begin{bmatrix} \lambda_1 \vec{u}_1 & \cdots & \lambda_n \vec{u}_n \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \\ \vdots \\ \vec{u}_n^T \end{bmatrix} = \lambda_1 \vec{u}_1 \vec{u}_1^T + \cdots + \lambda_n \vec{u}_n \vec{u}_n^T \end{aligned}$$

This representation of A is called a spectral decomposition of A because it breaks up A into pieces determined by the spectrum (eigenvalues) of A . Each term is an $n \times n$ matrix of rank 1. Furthermore, each matrix $\vec{u}_j \vec{u}_j^T$ is a projection matrix onto the subspace spanned by \vec{u}_j .

Example 4 Consider an invertible symmetric 2×2 matrix A . Show that the linear transformation $T(\vec{x} = A\vec{x}$ maps the unit circle into an ellipse, and find the lengths of the semimajor and the semiminor axes of the ellipse in terms of the eigenvalues of A .

Solution

The spectral theorem tells us there is an orthonormal eigenbasis u_1, u_2 for T , with associated real eigenvalues λ_1, λ_2 . Suppose that $|\lambda_1| > |\lambda_2|$. These eigenvalues will be nonzero, since A is invertible. The unit circle consists of all vectors of the form

$$\vec{v} = \cos(t)u_1 + \sin(t)u_2$$

. The image of the unit circle will be

$$\begin{aligned} T(\vec{v}) &= \cos(t)T(u_1) + \sin(t)T(u_2) \\ &= \cos(t)\lambda_1 u_1 + \sin(t)\lambda_2 u_2 \end{aligned}$$

an ellipse whose semimajor axis has the length $\|\lambda_1 u_1\| = |\lambda_1|$, while the length of the semiminor axis is $\|\lambda_2 u_2\| = |\lambda_2|$. (See Figure 4).

